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国际申请号:

PCT/CN2005/002150

INTERNATIONAL APPLICATION NUMBER

国际申请日:

10.12月 2005 (10.12.2005)

INTERNATIONAL FILING DATE

发明名称:

SPECULATIVE CODE MOTION FOR MEMORY LATENCY HIDING

OF INVENTION

中华人民共和国国家知识产权局局长

COMMISSIONER OF THE STATE INTELLECTUAL PROPERTY
OFFICE OF THE PEOPLE'S REPUBLIC OF CHINA

田力普

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PCT

The undersigned requests that the present international application be processed according to the Patent Cooperation Treaty.

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International Application No.	
10 · 12月 2005 (10 · 12 · 2005)	
International Filing Date	
RO/CN 中华人民共和国国家知识产权局 PCT International Application	
Name of receiving Office and PCT International Application	
Applicant's or agent's file reference (if desired) (12 characters maximum) FPEL05150064	

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Name and address: (Family name followed by given name; for a legal entity, full official designation. The address must include postal code and name of country. The country of the address indicated in this Box is the applicant's State (that is, country) of residence if no State of residence is indicated below.) INTEL CORPORATION 2200 Mission College Blvd. Santa Clara, California 95052 United States of America	Telephone No. Facsimile No. Teleprinter No. Applicant's registration No. with the Office
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Box No. V DESIGNATIONS

The filing of this request constitutes under Rule 4.9(a), the designation of all Contracting States bound by the PCT on the international filing date, for the grant of every kind of protection available and, where applicable, for the grant of both regional and national patents.

However,

- ☐ DE Germany is not designated for any kind of national protection
- ☐ KR Republic of Korea is not designated for any kind of national protection
- ☐ RU Russian Federation is not designated for any kind of national protection

(The check-boxes above may be used to exclude (irrevocably) the designations concerned in order to avoid the ceasing of the effect, under the national law, of an earlier national application from which priority is claimed. See the Notes to Box No. V as to the consequences of such national law provisions in these and certain other States.)

Box No. VI PRIORITY CLAIM

The priority of the following earlier application(s) is hereby claimed:

Filing date of earlier application (day/month/year)	Number of earlier application	Where earlier application is:		
		national application: country or Member of WTO	regional application:* regional Office	international application: receiving Office
item (1)				
item (2)				
item (3)				

☐ Further priority claims are indicated in the Supplemental Box.

The receiving Office is requested to prepare and transmit to the International Bureau a certified copy of the earlier application(s) (only if the earlier application was filed with the Office which for the purposes of this international application is the receiving Office) identified above as:

- ☐ all items ☐ item (1) ☐ item (2) ☐ item (3) ☐ other, see Supplemental Box

* Where the earlier application is an ARIPO application, indicate at least one country party to the Paris Convention for the Protection of Industrial Property or one Member of the World Trade Organization for which that earlier application was filed (Rule 4.10(b)(ii)):

Box No. VII INTERNATIONAL SEARCHING AUTHORITY

Choice of International Searching Authority (ISA) (if two or more International Searching Authorities are competent to carry out the international search, indicate the Authority chosen; the two-letter code may be used):

ISA / CN

Request to use results of earlier search; reference to that search (if an earlier search has been carried out by or requested from the International Searching Authority):

Date (day/month/year) Number Country (or regional Office)

Box No. VIII DECLARATIONS

The following declarations are contained in Boxes Nos. VIII (i) to (v) (mark the applicable check-boxes below and indicate in the right column the number of each type of declaration):

		Number of declarations
<input type="checkbox"/> Box No. VIII (i)	Declaration as to the identity of the inventor	:
<input type="checkbox"/> Box No. VIII (ii)	Declaration as to the applicant's entitlement, as at the international filing date, to apply for and be granted a patent	:
<input type="checkbox"/> Box No. VIII (iii)	Declaration as to the applicant's entitlement, as at the international filing date, to claim the priority of the earlier application	:
<input type="checkbox"/> Box No. VIII (iv)	Declaration of inventorship (only for the purposes of the designation of the United States of America)	:
<input type="checkbox"/> Box No. VIII (v)	Declaration as to non-prejudicial disclosures or exceptions to lack of novelty	:

Box No. IX CHECK LIST; LANGUAGE OF FILING

This international application contains:

(a) in paper form, the following number of sheets:

request (including declaration sheets) : 4

description (excluding sequence listing and/or tables related thereto) : 18

claims : 8

abstract : 1

drawings : 7

Sub-total number of sheets : 38

sequence listing :

tables related thereto :

(for both, actual number of sheets if filed in paper form, whether or not also filed in computer readable form; see (c) below)

Total number of sheets : 38

(b) ☐ only in computer readable form (Section 801(a)(i))(i) ☐ sequence listing(ii) ☐ tables related thereto(c) ☐ also in computer readable form (Section 801(a)(ii))(i) ☐ sequence listing(ii) ☐ tables related thereto

Type and number of carriers (diskette, CD-ROM, CD-R or other) on which are contained the

☐ sequence listing:☐ tables related thereto:

(additional copies to be indicated under items 9(ii) and/or 10(ii), in right column)

This international application is accompanied by the following item(s) (mark the applicable check-boxes below and indicate in right column the number of each item):

1. ☒ fee calculation sheet : 12. ☒ original separate power of attorney : 13. ☐ original general power of attorney :4. ☐ copy of general power of attorney; reference number, if any:5. ☐ statement explaining lack of signature :6. ☐ priority document(s) identified in Box No. VI as item(s):7. ☐ translation of international application into (language):8. ☐ separate indications concerning deposited microorganism or other biological material :9. ☐ sequence listing in computer readable form (indicate type and number of carriers)(i) ☐ copy submitted for the purposes of international search under Rule 13ter only (and not as part of the international application) :(ii) ☐ (only where check-box (b)(i) or (c)(i) is marked in left column) additional copies including, where applicable, the copy for the purposes of international search under Rule 13ter :(iii) ☐ together with relevant statement as to the identity of the copy or copies with the sequence listing mentioned in left column :10. ☐ tables in computer readable form related to sequence listing (indicate type and number of carriers)(i) ☐ copy submitted for the purposes of international search under Section 802(b-quater) only (and not as part of the international application) :(ii) ☐ (only where check-box (b)(ii) or (c)(ii) is marked in left column) additional copies including, where applicable, the copy for the purposes of international search under Section 802(b-quater) :(iii) ☐ together with relevant statement as to the identity of the copy or copies with the tables mentioned in left column :11. ☐ other (specify):

Figure of the drawings which should accompany the abstract:

Language of filing of the international application: EN

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Next to each signature, indicate the name of the person signing and the capacity in which the person signs (if such capacity is not obvious from reading the request).



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1. Date of actual receipt of the purported international application:

10 - 12月 2005 (10 - 12 - 2005)

3. Corrected date of actual receipt due to later but timely received papers or drawings completing the purported international application:

4. Date of timely receipt of the required corrections under PCT Article 11(2):

5. International Searching Authority (if two or more are competent): ISA /

6. ☐ Transmittal of search copy delayed until search fee is paid

2. Drawings:

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FEE CALCULATION SHEET

Annex to the Request

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International Application No.

10.12.2005 (12.12.2005)
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FPEL05150064

Applicant

INTEL CORPORATION etc.

CALCULATION OF PRESCRIBED FEES

1. TRANSMITTAL FEE CNY500 T

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2. SEARCH FEE CNY1500 S

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International search to be carried out by CN

(If two or more International Searching Authorities are competent to carry out the international search, indicate the name of the Authority which is chosen to carry out the international search.)

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Where items (b) and/or (c) of Box No. IX apply, enter Sub-total number of sheets } 38
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i2 8 x CHF15 = CHF120 i2
number of sheets in excess of 30 fee per sheet

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SPECULATIVE CODE MOTION FOR MEMORY LATENCY HIDING

BACKGROUND

[0001] Network processors (NP) may be used for packet processing. However, the
5 latency for one external memory access in network processors may be larger than
the worst-case service time. Therefore, network processors may have a parallel
multiprocessor architecture, and perform asynchronous (non-blocking) memory
access operations, so that the latency of memory accesses can be overlapped with
computation work in other threads. For instance, an example of network processors
10 may process packets in its Microengine cluster, which consists of multiple
Microengines (programmable processors with packet processing capability)
running in parallel. Every memory access instruction may be non-blocking and
associated with an event signal. That is, in response to a memory access
instruction, other instructions following the memory access instruction may continue
15 to run during the memory access. The other instructions may be blocked by a *wait*
instruction for the associated event signal. When the associated event signal is
asserted, the wait instruction may clear the event signal and return to execution.
Consequently, all the instructions between the memory access instruction and the
wait instruction may be overlapped with the latency of the memory access.

20 BRIEF DESCRIPTION OF THE DRAWINGS

[0002] The invention described herein is illustrated by way of example and not by way
of limitation in the accompanying figures. For simplicity and clarity of illustration,
elements illustrated in the figures are not necessarily drawn to scale. For example,
the dimensions of some elements may be exaggerated relative to other elements

for clarity. Further, where considered appropriate, reference labels have been repeated among the figures to indicate corresponding or analogous elements.

- [0003] FIG. 1 illustrates an embodiment of a computing device.
- [0004] FIG. 2 illustrates an embodiment of a network device.
- [0005] FIG. 3 illustrates an embodiment of a method that may be used for memory latency hiding.
- [0006] FIGS. 4A-4C each illustrates an embodiment of a representation of a program that comprise a memory access instruction.
- [0007] FIGS. 5A and 5B are time sequence diagrams that each illustrates an
10 embodiment of a latency of a memory access instruction.
- [0008] FIGS. 6A and 6B each illustrates an embodiment of a representation of a compiler to enforce the dependence for a memory access instruction.
- [0009] FIGS. 7A-7C illustrate an embodiment of a speculative code motion for a wait instruction.
- [0010] FIG. 8 illustrates an embodiment of a compiler.

DETAILED DESCRIPTION

- [0011] The following description describes techniques to hide memory access latency. The implementation of the techniques is not restricted in network processors; it may be used by any execution environments for similar purposes. In the following
20 description, numerous specific details such as logic implementations, opcodes, means to specify operands, resource partitioning/sharing/duplication implementations, types and interrelationships of system components, and logic partitioning/integration choices are set forth in order to provide a more thorough understanding of the present invention. However, the invention may be practiced

without such specific details. In other instances, control structures and full software instruction sequences have not been shown in detail in order not to obscure the invention.

[0012] References in the specification to "one embodiment", "an embodiment", "an
5 example embodiment", etc., indicate that the embodiment described may include a particular feature, structure, or characteristic, but every embodiment may not necessarily include the particular feature, structure, or characteristic. Moreover, such phrases are not necessarily referring to the same embodiment. Further, when
10 a particular feature, structure, or characteristic is described in connection with an embodiment, it is submitted that it is within the knowledge of one skilled in the art to effect such feature, structure, or characteristic in connection with other embodiments whether or not explicitly described.

[0013] Embodiments of the invention may be implemented in hardware, firmware, software, or any combination thereof. Embodiments of the invention may also be
15 implemented as instructions stored on a machine-readable medium, which may be read and executed by one or more processors. A machine-readable medium may include any mechanism for storing or transmitting information in a form readable by a machine (e.g., a computing device). For example, a machine-readable medium may include read only memory (ROM); random access memory (RAM); magnetic
20 disk storage media; optical storage media; flash memory devices; electrical, optical, acoustical or other forms of propagated signals (e.g., carrier waves, infrared signals, digital signals, etc.), and others.

[0014] An example embodiment of a computing device 100 is shown in FIG. 1. The computing device 100 may comprise one or more processors 110 coupled to a
25 chipset 120. The chipset 120 may comprise one or more integrated circuit

packages or chips that couple the processor 110 to system memory 130, storage device 150, and one or more I/O devices 160 such as, for example, mouse, keyboard, video controller, etc. of the computing device 100.

[0015] Each processor 110 may be implemented as a single integrated circuit, multiple
5 integrated circuits, or hardware with software routines (e.g., binary translation routines). The processor 110 may perform actions in response to executing instructions. For example, the processor 110 may executes programs, performs data manipulations and control tasks in the computing device 100. The processor
110 may be any type of processor adapted to execute instructions from memory
10 130, such as a microprocessor, a digital signal processor, a microcontroller, or another processor.

[0016] The memory 130 may comprise one or more different types of memory devices such as, for example, dynamic random access memory (DRAM) devices, static random access memory (SRAM) devices, read-only memory (ROM) devices,
15 and/or other volatile or non-volatile memory devices. The memory 120 may store instructions and codes represented by data signals that may be executed by processor 110. In one embodiment, a compiler 140 may be stored in the memory 120 and implemented by the processor 110. The compiler 140 may comprise any type of compiler adapted to generate data, code, information, etc., that may be
20 stored in memory 130 and accessed by processor 110.

[0017] The chipset 120 may comprise a memory controller 180 that may control access to the memory 130. The chipset 120 may further comprise a storage device interface (not shown) that may access the storage device 150. The storage device
150 may comprise a tape, a hard disk drive, a floppy diskette, a compact disk (CD)
25 ROM, a flash memory device, other mass storage devices, or any other magnetic or

optic storage media. The storage device 150 may store information, such as code, programs, files, data, applications, and operating systems. The chipset 120 may further comprise one or more I/O interfaces (not shown) to access the I/O device 160 via buses 112 such as, for example, peripheral component interconnect (PCI) buses, accelerated graphics port (AGP) buses, universal serial bus (USB) buses, low pin count (LPC) buses, and/or other I/O buses.

[0018] The I/O device 160 may include any I/O devices to perform I/O functions.

Examples of the I/O device 160 may include controller for input devices (e.g., keyboard, mouse, trackball, pointing device), media card (e.g., audio, video, graphics), network card, and any other peripheral controllers.

[0019] An embodiment of a network device 200 is shown in FIG. 2. The network device 200 may enable transfer of packets between a client and a server via a network.

The network device 200 may comprise a network interface 210, a network processor 220, and a memory 250. The network interface 210 may provide physical, electrical, and protocol interfaces to transfer packets. For example, the network interface 210 may receive a packet and send the packet to the network processor 220 for further processing.

[0020] The memory 250 may store one or more packets and packet related information that may be used by the network processor 220 to process the packets. In one embodiment, the memory 250 may store packets, look-up tables, data structures that enable the network processor 220 to process the packets. In one embodiment, the memory 250 may comprise a dynamic random access memory (DRAM) and a static random access memory (SRAM).

[0021] The network processor 220 may receive one or more packets from the network interface 210, process the packets, and send the packets to the network interface

210. In one embodiment, the network processor 220 may comprise a network processor, for example, Intel® IXP2400 network processor. The network processor 220 may comprise a memory controller 240 that may control access to memory 250. For example, the network processor 220 may perform asynchronous or
 5 non-blocking memory access operations on memory 250 under control of the memory controller 240. In one embodiment, the memory controller 240 may be located outside the network processor 220.

[0022] The network processor 220 may further comprise microengines 230-1 through 230-N that may run in parallel. The microengine 230-1 through 230-N may
 10 cooperatively operate to process the packets. Each microengine may process a portion of the packet processing task. The processing of a packet may comprise sub-tasks such as packet validation, IP lookup, determining the type of service (TOS), time to live (TTL), out going address and the MAC address. In one embodiment, each microengine may comprise one or more threads and each
 15 thread may perform a sub-task. For example, the microengine 230-1 may comprise threads such as 231-0 to 231-3. However, other embodiments may comprise a different number of threads such as, for example, eight threads. Each microengine may comprise a signal register file and a pseudo register file. For example, the microengine 230-1 may comprise a signal register file 234 and a pseudo register file
 20 236. The signal register file 234 may comprise one or more registers that each may store an asynchronous signal corresponding to a memory access instruction. The pseudo register file 236 may comprise one or more registers that each may store a pseudo signal.

[0023] In the following, an example embodiment of a process as shown in FIG. 3 will be
 25 described in combination with FIGs. 4-7. In block 302, the compiler 140 may extract

from an I/O instruction or memory access instruction an asynchronous signal that may represent latency associated with the I/O instruction. In one embodiment, the I/O instruction or memory access instruction may comprise a store instruction, a load instruction, etc. For a program 400 as shown in FIG. 4A, the compiler 140 may
5 extract an asynchronous signal *s* from a store instruction 412. After the extraction, the compiler 140 may represent the store instruction 412 as a store instruction 422 (FIG. 4B) associated with the asynchronous signal *s*. The compiler 140 may further generate a wait instruction 424 that wait the asynchronous signal *s*. In one
embodiment, the signal register file 234 may comprise a signal register to store the
10 asynchronous signal *s*. As shown in FIG. 4C, the asynchronous signal *s* may represent a dependence or dependence constraint, for example, between the store instruction 422 and the wait instruction 424 explicitly in the compiler 140, so that optimization of the latency, as well as other optimizations, may continue to work on the dependence of the program 400.

[0024] In order to enforce the dependence between a memory access instruction and a wait instruction, the compiler 140 may use a relationship of define and use. For example, referring to an internal representation of the compiler 140 as shown in FIG. 6A, the compiler 140 may make a store instruction 612 define an asynchronous signal extracted from the store instruction 612. The compiler 140 may further make
20 a wait instruction 614 wait for or use the asynchronous signal. Similarly, as shown in FIG. 6B, the compiler 140 may make a load instruction 622 define an asynchronous signal extracted from the load instruction 622 and may make a wait instruction 624 wait for or use the asynchronous signal. In one embodiment, a signal register to store the asynchronous signal may be introduced in a network device, for example,
25 as shown in FIG. 2. For example, the signal register file 234 of FIG. 2 may comprise

one or more signal registers that may each store an asynchronous signal extracted from a memory access instruction.

[0025] Referring to FIGS. 5A and 5B, embodiments of instructions that may have dependence on associated wait instructions are illustrated. As shown in FIG. 5A, after issue of a load instruction, $R1 = \text{load } [R2]$, signal s (512), an instruction, $R2 = R1 + 1$, that uses a result $R1$ of the load instruction has to wait for the completion of the load operation (516), i.e., after the asynchronous signal of the load instruction is asserted and the result $R1$ is ready (514). The instruction may not be overlapped with latency A of the load instruction. Similarly, FIG. 5B illustrates a similar situation for an instruction, $R2 = R3 + 1$, that overwrites a source $R2$ of a store instruction, $[R1] = \text{store } R2$, signal.

[0026] In order to enforce a dependence of an instruction that depends on the completion of a memory access instruction and a wait instruction associated with the memory access instruction, the compiler 140 may also employ a relationship of define and use. In one embodiment, the compiler 140 may introduce a pseudo signal register for each signal register for a memory access instruction. Referring to the internal representation as shown in FIG. 6A, the compiler 140 may make the wait instruction 614 define a pseudo signal corresponding to the asynchronous signal extracted from the store instruction 612. The compiler 140 may further make an instruction 616 that depends on the completion of the store instruction 612 use the pseudo signal. Similarly, FIG. 6B illustrates another embodiment relating to a load instruction. In one embodiment, the pseudo register file 236 of FIG. 2 may comprise one or more pseudo signal registers that may each store a pseudo signal.

[0027] In one embodiment, the compiler 140 may map a register number to a signal register and a pseudo register. An example of the codes may be as follows, wherein *V2SP* may represent the corresponding signal register and pseudo register:

Map of int to pair: V2SP

[0028] In another embodiment, the compiler 140 may use the following codes to express the define-use relation as *DU* and organize the define-use relation *DU* as webs, wherein *R* is the number of register accesses:

Relation of R to R: DU;
PartitionSet of R: webs;

[0029] The following codes may be used by the compiler 140 to extract asynchronous
10 signals and introduce pseudo signals to enforce the dependence for load instructions in a program. For example, the compiler 140 may execute the following operation:

Build def-use relation for the registers defined in
all load instructions in the program

[0030] Then, the compiler 140 may construct webs based on *DU* relation, wherein *r1*
15 and *r2* may represent a pair of two factors in *DU*, i.e., define and use. For example:

For each pair <r1, r2> in DU
Join r1 and r2 in webs;

[0031] In one embodiment, for each partition *w* in the webs, the compiler 140 may further map a register number *v* to a pair of signal *s* and pseudo *p* to obtain *s* and *p* from the corresponding signal register and pseudo register *V2SP[v]*. For each
20 factor *r* in each partition *w*, the compiler 140 may further determine whether the register number *v* is defined in an instruction *i*. If yes, the compiler 140 may further make the instruction *i* define *s* explicitly. If not, the compiler 140 may generate a wait instruction to wait for signal *s* and make the wait instruction define *p* and use *s*

explicitly, in response to determining that the instruction i is a load instruction. The compiler 140 may further make the instruction i use p explicitly, in response to determining that v is used in the instruction i . An example of the corresponding codes may be as follows:

```

For each partition  $w$  in the webs
{
    /*  $w$ 's register number is  $v$  */
     $\langle s, p \rangle = V2SP[v]$ ; /* map  $v$  to signal  $s$  and pseudo  $p$  */
    for each occurrence  $r$  of  $w$ 
    {
        /*  $i$  is the container instruction */
        if ( $v$  is defined here)
        {
            Make  $i$  define  $s$  explicitly;
            if ( $i$  is a load instruction )
                Generate an instruction to wait signal  $s$ 
                and make the wait instruction define  $p$  and use  $s$ 
                explicitly;
            else /*  $v$  is used here */
            {
                Make  $i$  use  $p$  explicitly;
            }
        }
    }
}

```

5

[0032] Similarly, an example algorithm is shown as follows for the compiler 140 to extract asynchronous signals and introduce pseudo signals to enforce the dependence for store instructions, wherein the compiler 140 may use use-define relation UD .

FIG. 4B

```

Build use-define relation for the registers used in all
store instructions in the program;
/*Construct webs based on UD relation */
For each pair <r1,r2 > in UD
    Join r1 and r2 in webs;
For each partition w in the webs
{
    /* w's register number is v*/
    <s, p>=V2SP[v]; /*map v to signal s and pseudo p*/
    for each occurrence r of w
    {
        /* i is the container instruction */
        if (v is used here)
        {
            Make i define s explicitly;
            if (i is a store instruction)
                Generate an instruction to wait signal s
                and make the wait instruction define p and use s
                explicitly;
        } else /* v is defined here */
        {
            Make i use p explicitly;
        }
    }
}

```

[0033] In order to schedule as many instructions as possible between issue of a memory access operation and its completion, the compiler 140 may perform code motion subject to the dependence constraint or order/relationship of instructions defined in a program. In block 304, the compiler 140 may further perform a first stage of code motion. For example, the compiler 140 may recognize a first set of one or more instructions in a program except I/O instructions as motion candidates and move the candidates forward subject to the dependence constraint of the program through one or more paths in the flow graph of the program. In one embodiment, the first stage of code motion may comprise a code sinking operation. For example, for the program as shown in FIG. 4B, the compiler 140 may recognize instructions 426 and the wait instruction 424 as motion candidates and may move

these instructions forward while fixing the location of memory access instruction 422, so that a number of instructions between the issue and the completion of the memory access instruction 422 may be increased subject to a dependence constraint in the program.

[0054] In one embodiment, in the first stage of code motion, compiler 140 may further adopt speculative code motion for wait instructions, for example, in a situation as shown in FIG. 7A. FIG. 7A illustrates an embodiment of a flow graph, wherein block 710 is a merging predecessor block for blocks 720 and 730 that are two predecessor blocks for block 740; and block 740 is a merging successor block of blocks 720 and 730; however, other embodiments may comprise a different structure. The first predecessor block 720 may comprise a wait instruction 724 associated with a memory access instruction 722. The second predecessor block 730 does not comprise a wait instruction. In this situation, the compiler 140 may not move forward or sink the wait instruction 724 into the merging successor block 740 of the blocks 720 and 730 even if the dependence constraint of the flow graph allows.

[0035] In order to perform the first stage of code motion speculatively, for example, in the situation as shown in FIG. 7A, in one embodiment, the compiler 140 may further insert or append one or more compensation codes to the second predecessor block 730. Referring to FIG. 7B, the compiler 140 may insert a signal sending instruction 734 and a second wait instruction 736 into the second predecessor block 730. The signal sending instruction 734 may send the asynchronous signal of the memory access instruction 722 to the second predecessor block 730 subject to the dependence constraint of the flow graph. The compiler 140 may generate a second wait instruction 736 that waits for the asynchronous signal in block 730. Then, as

shown in FIG. 7C, the compiler 140 may remove the two wait instructions 722 and 736 from blocks 720 and 730, respectively. The compiler 140 may further prepend an instruction instance 742 of wait instructions 722 and 736 to the merging successor block 740 while fixing the memory access instruction 722 subject to the
5 dependence constraint of the flow graph, so that a number of instructions between the issue and the completion of the memory access instruction 722 may be increased.

[0036] In block 306, the compiler 140 may perform a second stage of code motion. In one embodiment, the compiler 140 may recognize a second set of one or more
10 instructions in the program except wait instructions as motion candidates and move the candidates backward subject to the dependence constraint through the paths in the program. In one embodiment, the second stage of code motion may comprise a code hoisting operation. In another embodiment, for a motion candidate that depends on the completion of a memory access instruction, the compiler 140 may
15 move the candidate backward to follow a wait instruction associated with the memory access instruction so as to accord with the dependence constraint between the candidate and the wait instruction. In one embodiment, the second instruction set may comprise one or more instructions that are comprised in the first instruction set.

[0037] In one embodiment, the compiler 140 may perform a code sinking operation with I/O instruction fixed and a code hoisting operation with wait instruction fixed; however, in another embodiment, the compiler 140 may perform in a program, for example, a code hoisting operation with wait instruction fixed and a code sinking operation with I/O instruction fixed subject to dependence constraint of the
25 program.

[0038] In the following, a description will be made on an example of codes that may be used by the compiler 140 to perform speculative code motion for wait instructions. In one embodiment, the compiler 140 may use the following codes to map an instruction *i* in a program to a motion candidate *c* (*NC*):

5

Map of int to int : NC ;

[0039] The compiler 140 may map two instructions in a program to the same motion candidate *NC*, in response to determining that the two instructions are syntactically the same.

[0040] In another embodiment, the compiler 140 may use the following code to represent a number of occurrence of an instruction in predecessor blocks as *SinkCandidates*, wherein the instruction is ready to sink into a successor block of the predecessor blocks subject to a dependence constraint:

Vector of int: SinkCandidates ;

[0041] In one embodiment, the compiler 140 may build a map of motion candidates *NC* in a program, build a flow graph *G* for the program, and initialize a work queue *Sinkqueue* with basic blocks based on a topological order in the flow graph *G*. For example:

Build the map of NC that maps an instruction i to motion candidate c ;
Build the flow graph G for the program ;
Initialize a WorkQueue (SinkQueue) with basic blocks
based on the topological order in graph G

[0042] The compiler 140 may determine whether the work queue is empty or not. In response to determining that the work queue comprises at least one basic block, the compiler 140 may dequeue a basic block *b* from the *SinkQueue*. The compiler 140 may further build a set for all predecessor blocks of the basic block *b* as *Predecessors*. For each predecessor block *p*, the compiler 140 may put each

instruction *i* in *p* into a set of *Ready*, in response to determining that *i* is ready to sink into the basic block *b* subject to the dependence constraint of the program.

```

While (SinkQueue is not empty)
{
    Dequeue a basic block b from SinkQueue;
    Build a set Predecessors for all predecessors of b;
    For each basic block p in Predecessors
        For each instruction i in basic block p
            if i is ready to sink into basic block b subject to dependence constraint
                Put i into the set of Ready;

```

[0033] In response to determining that the *SinkQueue* is not empty, the compiler 140 may further determine whether the set of *Ready* is empty. In response to determining that *Ready* comprises at least one instruction, i.e., not empty, the compiler 140 may further reset a number of ready instructions for each motion candidates or predecessor block *SinkCandidates*. For example:

```

while(Ready is not empty)
{
    /*reset the number of the ready instructions for each motion candidate to 0 */
    10    Reset SinkCandidates;

```

[0044] For each instruction *i* in *Ready*, the compiler 140 may record or calculate *SinkCandidates*[*NC*[*i*]], i.e., a number of occurrence of the instruction *i* in different predecessors of the basic block *b*. For each instruction *i* in *Ready*, in response to

15 determining that the number *SinkCandidates*[*NC*[*i*]] is less than the number of predecessor blocks of *b*, the compiler 140 may further determine whether the current candidate is a wait instruction. In response to determining that the current candidate is a wait instruction, the compiler 140 may append compensation code to the predecessor blocks where the current candidate is not ready, such as a

20 situation shown in FIG. 7A and make *SinkCandidates*[*NC*[*i*]] equal to the number of predecessor blocks of *b* (FIG. 7B). On the other hand, for each instruction *i* in

Ready, in response to determining that *SinkCandidates*[*NC*[*i*]] equals to the number of predecessor blocks of *b*, the compiler 140 may remove all instructions corresponding to the current candidate from all predecessor blocks of *b* and prepend an instruction instance of the candidate to *b* (FIG. 7C). The compiler 140

5 may further update the dependence constraint relating to all predecessor blocks and may update the set of *Ready*. An example of codes may be as follows:

```

For each instruction i in Ready
{
    SinkCandidates [NC[i]]++;
}
For each instruction i in Ready
{
    if(SinkCandidates[NC[i]] < The number of predecessors of b)
    {
        if(The current candidate which NC[i] indicates is a WAIT instruction)
        {
            Append the compensation code to the blocks in
            Predecessors where this candidate is not ready;
            SinkCandidates[NC[i]] = The number of predecessors of b;
        }
    }
    if(SinkCandidates[NC[i]] == The number of predecessors of b)
    {
        Remove all the instructions corresponding to this candidate
        from all the predecessors of b;
        Prepend an instruction instance of this candidate to basic block b;
        Update the dependence constraint of all predecessor blocks ;
        Update the Ready set ;/* May introduce more ready instructions */
    }
}

```

[0045] In another embodiment, the compiler 140 may further enqueue successor

10 blocks of the current block *b* of *G* in *SinkQueue*, in response to any change when the *SinkQueue* is not empty. For example:

If any change happens, enqueue the current block's successors in G in SinkQueue

[0046] FIG. 8 is a block diagram that illustrates a compiler 800 according to an embodiment of the present invention. The compiler 800 may comprise a compiler manager 810. The compiler manager 810 may receives source code to compile. The compiler manager 810 may interface with and transmit information between
5 other components in the compiler 800.

[0047] The compiler 800 may comprise a front end unit 820. In one embodiment, the frond end unit 820 may parse source code. An intermediate language unit 830 in the compiler 800 may transforms the parsed source code from the front end unit 820 into one or more common intermediate forms, such as an intermediate
10 representation. For example, referring to FIG. 6A and 6B, the intermediate language unit 820 may extract an asynchronous signal from a memory access instruction and may define the asynchronous signal in the memory access instruction explicitly. The intermediate language unit 820 may further make a wait instruction associated with the memory access instruction wait for or use the
15 asynchronous signal and may define a pseudo signal associated with the asynchronous signal, with reference to 614 and 624 in FIGs. 6A and 6B. The intermediate language unit 820 may make a memory access dependent instruction, such as 616 and 626 in FIGs. 6A and 6B, use the pseudo signal. In one embodiment, a network device, for example, as shown in FIG. 2, may comprise a
20 signal register and a pseudo register to store the asynchronous signal and the pseudo signal, respectively.

[0048] In one embodiment, the compiler 800 may further comprise a code motion unit 840. The code motion unit 840 may perform, for example, global instruction scheduling. In one embodiment, the code motion unit 840 may perform code motion
25 as described in blocks 304 and 306 of FIG. 3. For example, the code motion unit

840 may move an instruction from a predecessor block into a successor block subject to a dependence constraint of a program, for example, as shown in FIG. 7C. In another embodiment, the code motion unit 840 may move an instruction from a successor block into a predecessor block subject to a dependence constraint of a program. In yet another embodiment, the code motion unit 840 may perform speculative code motion for wait instructions subject to a dependence constraint of a program, for example, as shown in FIGs. 7B and 7C. In one embodiment, the compiler 800 may comprise one or more code motion unit 840 that may each perform one code motion, such as, for example, a first code motion, a second code motion and/or a speculative code motion. In another embodiment, the compiler 800 may comprise other code motion units for different code motions.

[0049] The compiler 800 may further comprise a code generator 850 that may convert the intermediate representation into machine or assembly code.

[0050] While certain features of the invention have been described with reference to embodiments, the description is not intended to be construed in a limiting sense. Various modifications of the embodiments, as well as other embodiments of the invention, which are apparent to persons skilled in the art to which the invention pertains are deemed to lie within the spirit and scope of the invention.

What is claimed is:

1. A method comprising:
 extracting an asynchronous signal from a memory access instruction in a
 program to represent a latency of the memory access instruction; and
 5 generating a wait instruction to wait for the asynchronous signal.

2. The method of claim 1, further comprising:
 enforcing a first dependence between the memory access instruction and
 the wait instruction via the asynchronous signal.

10 3. The method of claim 1, further comprising:
 introducing a pseudo signal to enforce a second dependence between the
 wait instruction and a memory access dependent instruction.

4. The method of claim 1, further comprising:
 15 making the memory access instruction define the asynchronous signal; and
 making the wait instruction use the asynchronous signal.

5. The method of claim 1, further comprising:
 making the wait instruction define a pseudo signal; and
 20 making an instruction that depends on the completion of the memory access
 instruction use the pseudo signal.

6. The method of claim 1, further comprising:
 storing the asynchronous signal in a signal register of a network device.

7. The method of claim 3, further comprising:

storing the pseudo signal in a pseudo signal register of a network device.

5 8. A method, comprising subject to a dependence constraint of a program:

performing a first code motion on a first set of one or more instructions

except each memory access instruction in the program, and

performing a second code motion on a second set of one or more

instructions except each wait instruction in the program, to increase a number of

10 instructions between issue and completion of the memory access instruction.

9. The method of claim 8, wherein the first code motion comprises moving

the first instruction set forward through one or more paths of the program with the

memory access instructions fixed, and the second code motion comprises moving

15 the second instruction set backward through the one or more paths of the program

with the wait instructions fixed.

10. The method of claim 8, wherein the first code motion comprises sinking

the one or more instructions in the first set that occur in each predecessor block of a

20 successor block into the successor block, and the second code motion comprises

hoisting the one or more instructions in the second set.

11. The method of claim 8, comprising:

performing a speculative code motion on a wait instruction, in response to determining that the wait instruction is absent in at least one predecessor blocks of a successor block.

5

12. The method of claim 8, comprising:

in response to determining that the number of occurrence of a wait instruction in predecessor blocks of a successor block is less than the number of the predecessor blocks, appending a compensation code for the wait instruction to one or more predecessors that lack the wait instruction;

10

removing the wait instruction from the predecessors; and

prepending an instruction instance of the wait instruction to the successor block.

15

13. A compiler, comprising:

a code motion unit to perform code motion in a program subject to a dependence constraint of the program to hide a latency of a memory access instruction in the program.

20

14. The compiler of claim 13, further comprising:

an intermediate language unit to represent a memory access instruction in a program with an asynchronous signal associated with a latency of the memory access instruction.

25

15. The compiler of claim 13, further comprising:

an intermediate language unit to define an asynchronous signal in the memory access instruction to represent the latency and to generate a wait instruction that uses the asynchronous signal.

5 16. The compiler of claim 13, further comprising:

an intermediate language unit to define a pseudo signal in a wait instruction associated with the memory access instruction and to make an instruction that depends on the memory access instruction use the pseudo signal.

10 17. The compiler of claim 13, wherein the code motion unit further to move a wait instruction associated with the memory access instruction and a first set of one or more instructions in a first direction subject to the dependent constraint, with the memory access instruction fixed; and

15 move the memory access instruction and a second set of one or more instructions in the program subject to the dependent constraint in a second direction that is opposite to the first direction, with the wait instruction fixed.

18. The compiler of claim 13, wherein the code motion unit further to sink a wait instruction associated with the memory access instruction and a first set of one or more instructions of the program from each predecessor block to a successor block at a merging point of the predecessor blocks subject to the dependence constraint of the program, in response to determining that each predecessor block comprises the wait instruction and the one or more instructions, with the memory access instruction fixed; and

20

hoist the memory access instruction and a second set of one or more instructions in the program subject to the dependent constraint, with the wait instruction fixed.

5 19. The compiler of claim 13, wherein the code motion unit further to perform a speculative code motion on a wait instruction associated with the memory access instruction, in response to determining that the wait instruction is present in a first predecessor block of a merging successor block of the program and is absent in a second predecessor block of the merging successor block.

10

 20. The compiler of claim 13, wherein the code motion unit further to recognize a wait instruction associated with the memory access instruction as a motion candidate subject to a dependence constraint of the program;

 in response to determining that the wait instruction is present in a first
15 predecessor block of the merging successor block and is absent in a second predecessor block of the merging successor block, insert a compensation code for the wait instruction into the second predecessor block; and

 sink the wait instruction into a merging successor block of the first and second predecessor blocks subject to the dependence constraint.

20

 21. The compiler of claim 20, wherein the code motion unit further to hoist the memory access instruction subject to the dependence constraint.

22. A machine readable medium comprising a plurality of instructions that in response to being executed result in a computing device

determining a motion candidate from one or more predecessor blocks of a
5 first block of a program based on a dependence constraint of the program; and
performing a code motion on an instruction corresponding to the motion
candidate to hide a latency associated with a memory access instruction.

23. The machine readable medium of claim 22, wherein the machine
10 readable medium further comprising instructions that in response to being executed
result in the computing device

in response to determining that a number of occurrence of the candidate in
the predecessor blocks is smaller than a number of predecessor blocks and in
response to determining that the candidate is a wait instruction, appending a
15 compensation code to one or more of the predecessor blocks where the candidate
is absent.

24. The machine readable medium of claim 23, wherein the machine
readable medium further comprising instructions that in response to being executed
20 result in the computing device

appending a wait instruction corresponding to the candidate to each of said
one or more predecessor blocks where the candidate is absent.

25. The machine readable medium of claim 24, wherein the machine readable medium further comprising instructions that in response to being executed result in the computing device

5 sinking each wait instruction corresponding to the candidate in each predecessor blocks of the first block into the first block.

26. The machine readable medium of claim 22, wherein the machine readable medium further comprising instructions that in response to being executed result in the computing device

10 in response to determining that a number of occurrence of the candidate in the predecessor blocks equals to a number of the predecessor blocks, removing each instruction corresponding to the candidate from each predecessor block of the first block; and

15 prepending an instruction instance of the candidate to the first block.

27. The machine readable medium of claim 26, wherein the machine readable medium further comprising instructions that in response to being executed result in the computing device

20 updating a dependent constraint of predecessor blocks of the first block.

28. The machine readable medium of claim 22, wherein the machine readable medium further comprising instructions that in response to being executed result in the computing device

5 determining a sinking candidate from one or more instructions of the program except the memory access instruction, based on a dependence constraint of the program;

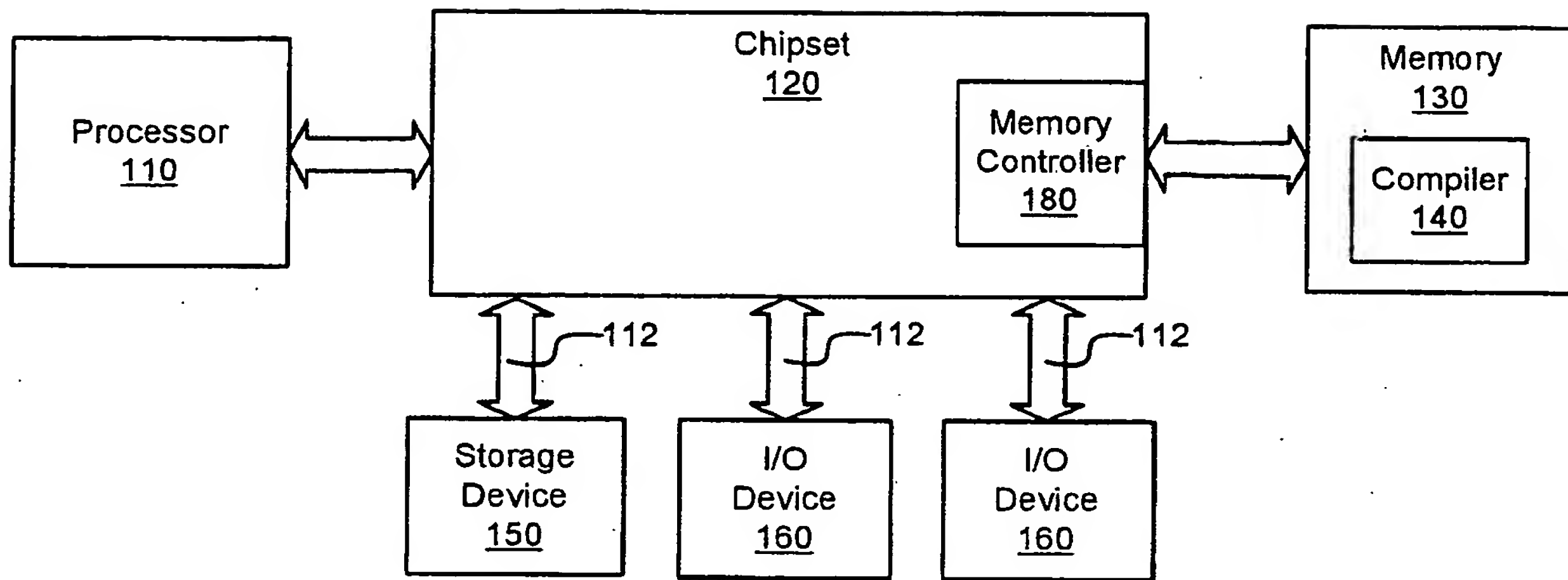
performing a code sinking on each instruction corresponding to the sinking candidate subject to the dependence constraint;

10 determining a hoisting candidate from one or more instructions of the program except a wait instruction associated with the memory access instruction, based on the dependence constraint of the program; and

performing a code hoisting on each instruction corresponding to the hoisting candidate subject to the dependence constraint.

ABSTRACT

Various embodiments that may be used in performing speculative code motion for memory latency hiding are disclosed. One embodiment comprises extracting an asynchronous signal from a memory access instruction in a program
5 to represent a latency of the memory access instruction, and generating a wait instruction to wait the asynchronous signal.



100

FIG. 1

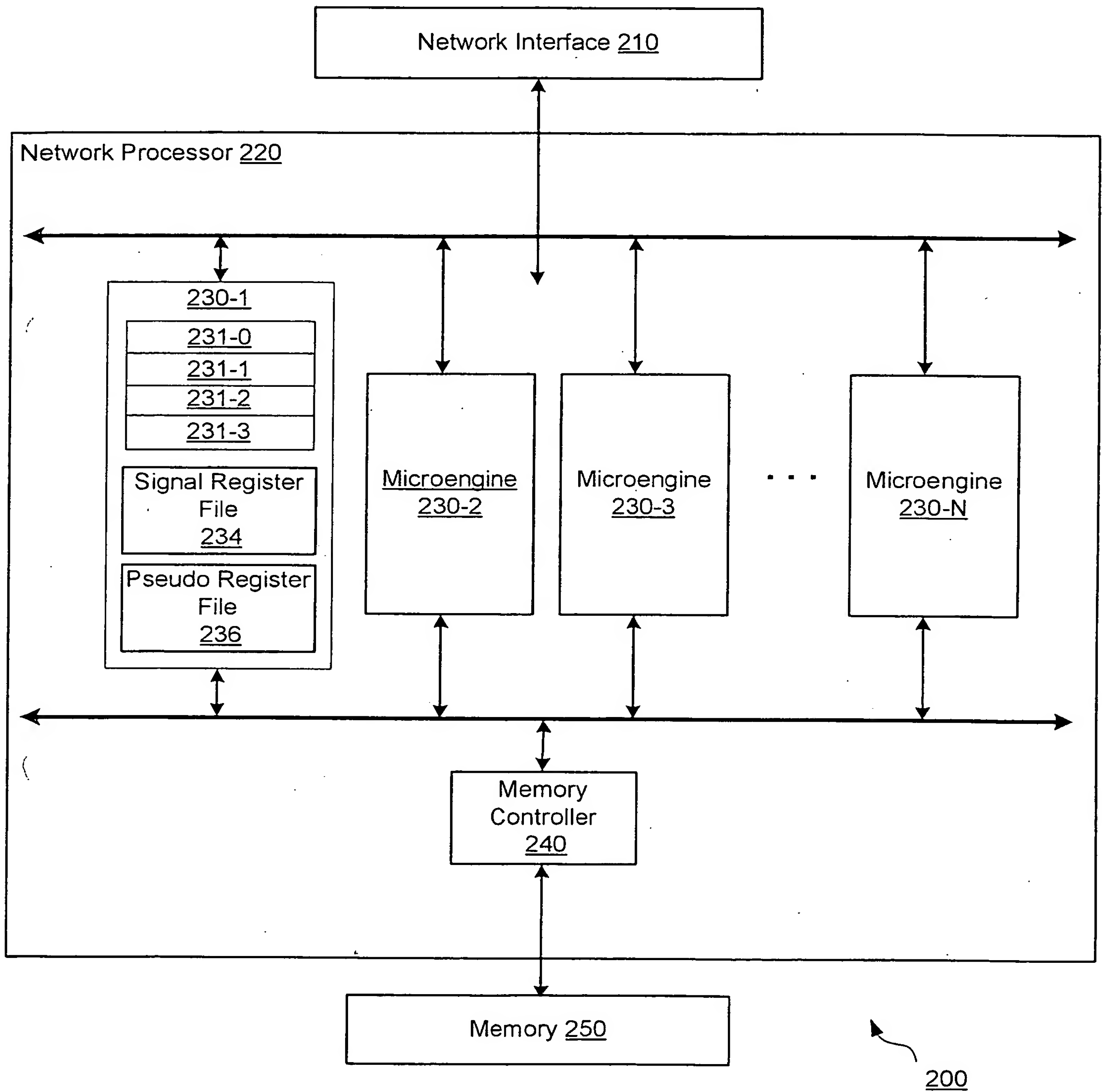


FIG. 2

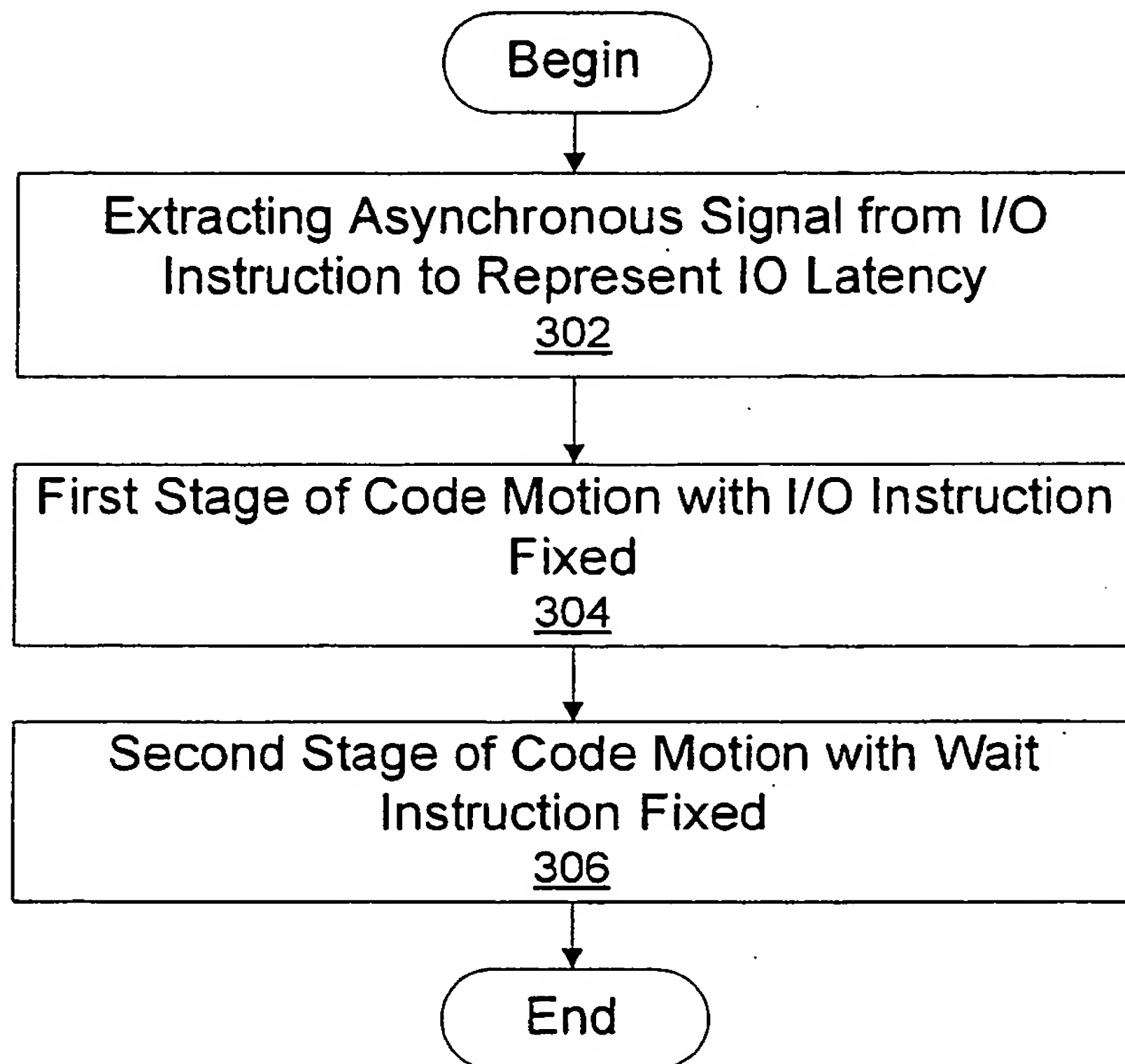


FIG. 3

[R2]=store R1 412
 R3=R2+1

 R4=R3<<2
 R1=R5-R4

400

FIG. 4A

[R2]=store R1, signal s 422
 Wait s 424
 R3=R2+1

 R4=R3<<2 426
 R1=R5-R4

FIG. 4B

[R2]=store R1, signal s
 ↓
 Wait s
 ↓
 R1=R5-R4 436

FIG. 4C

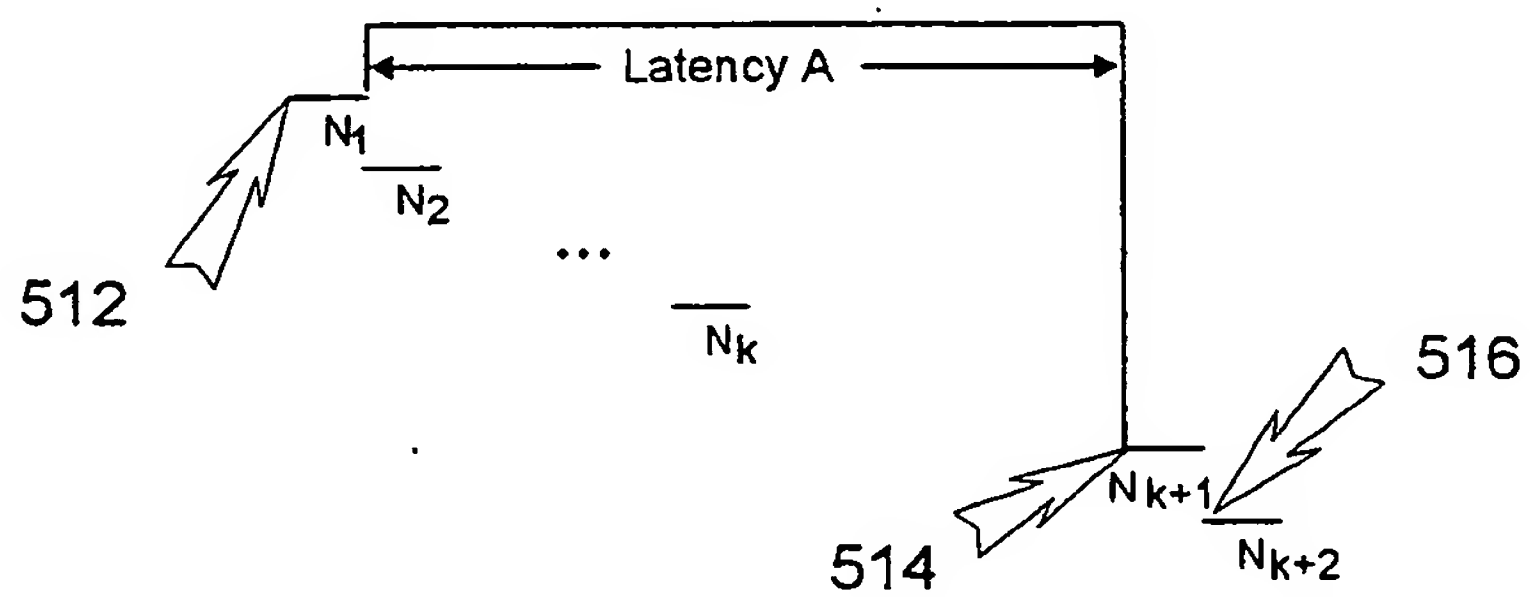


FIG. 5A

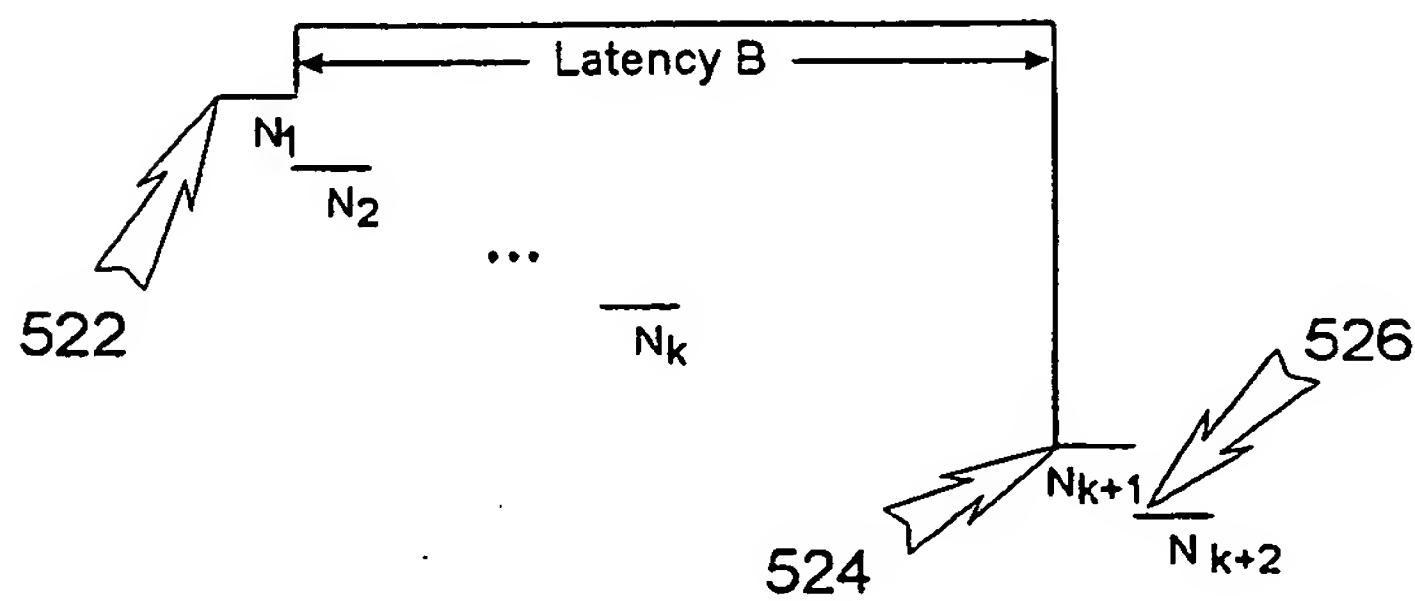


FIG. 5B

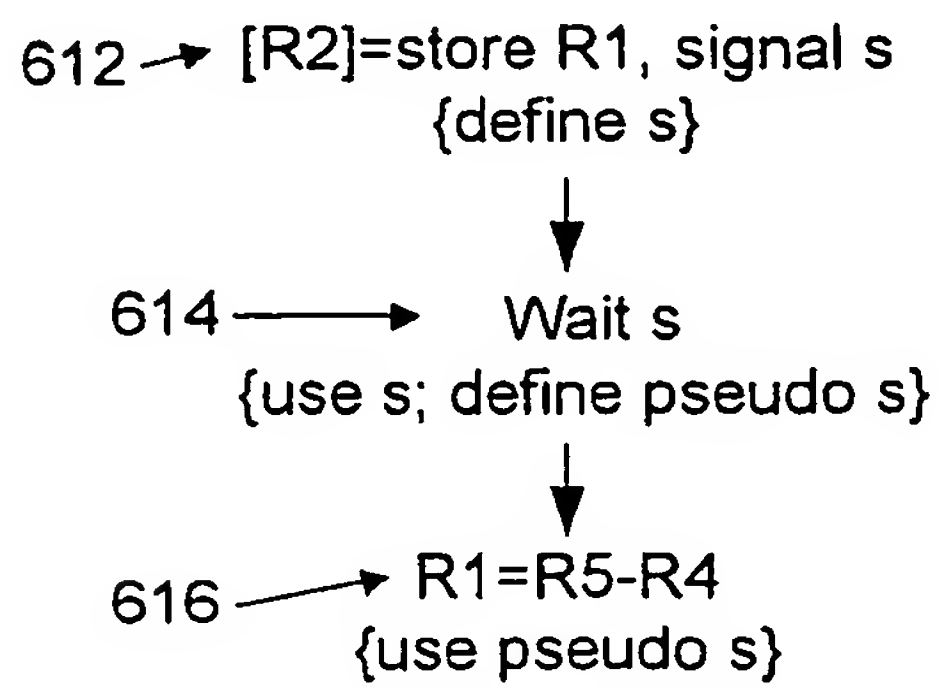


FIG. 6A

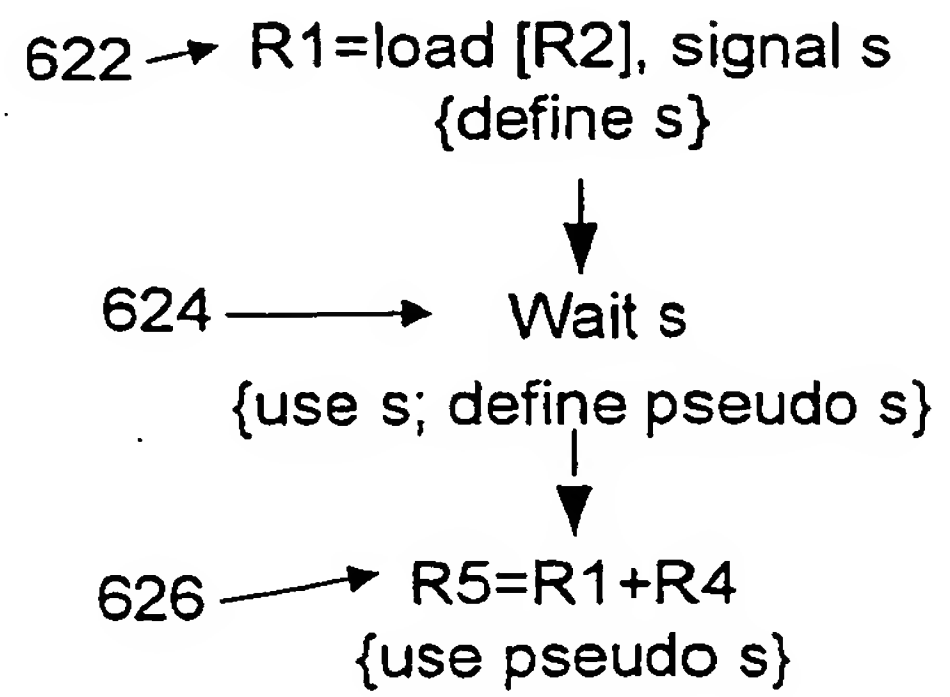


FIG. 6B

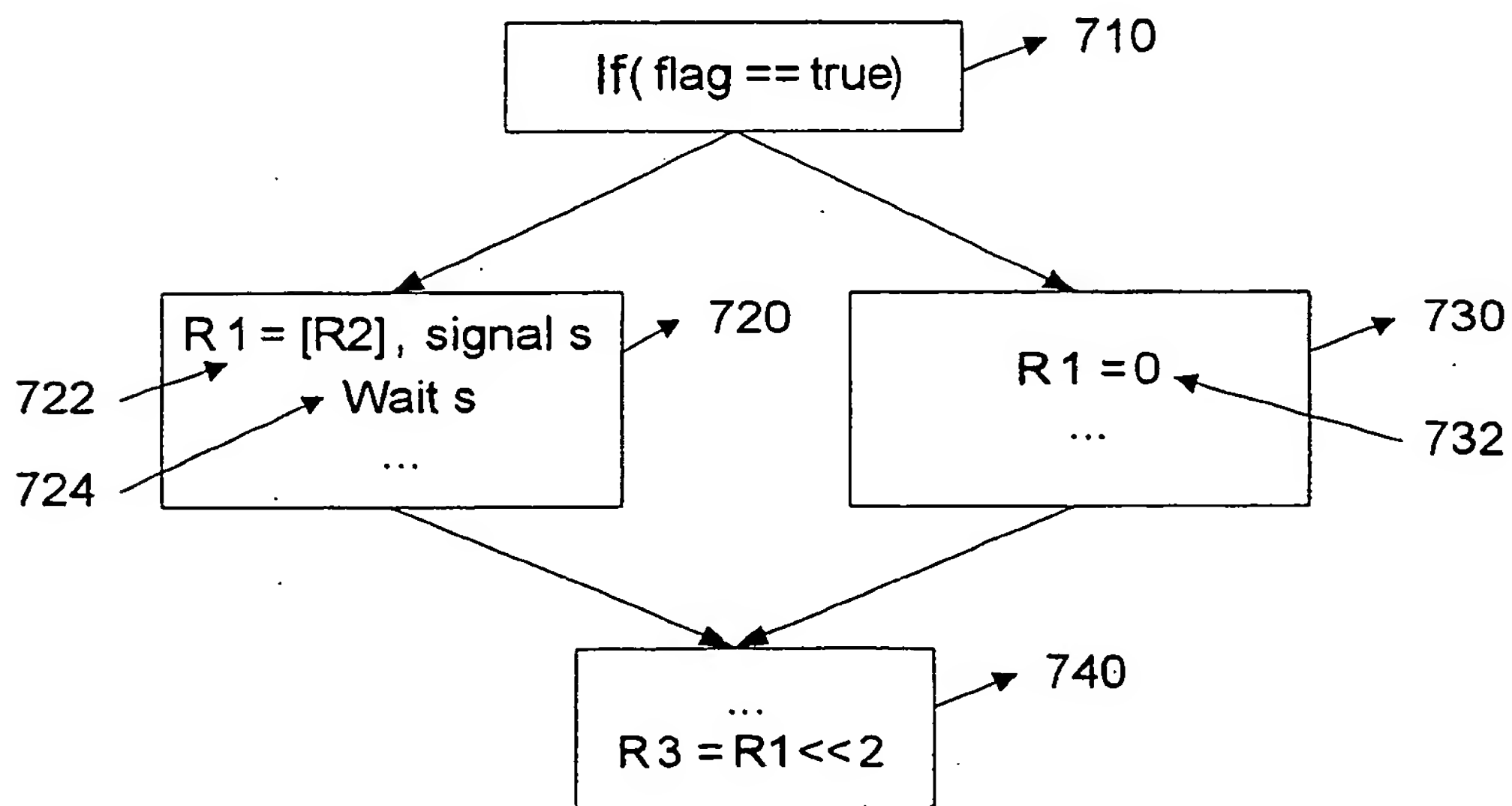


FIG. 7A

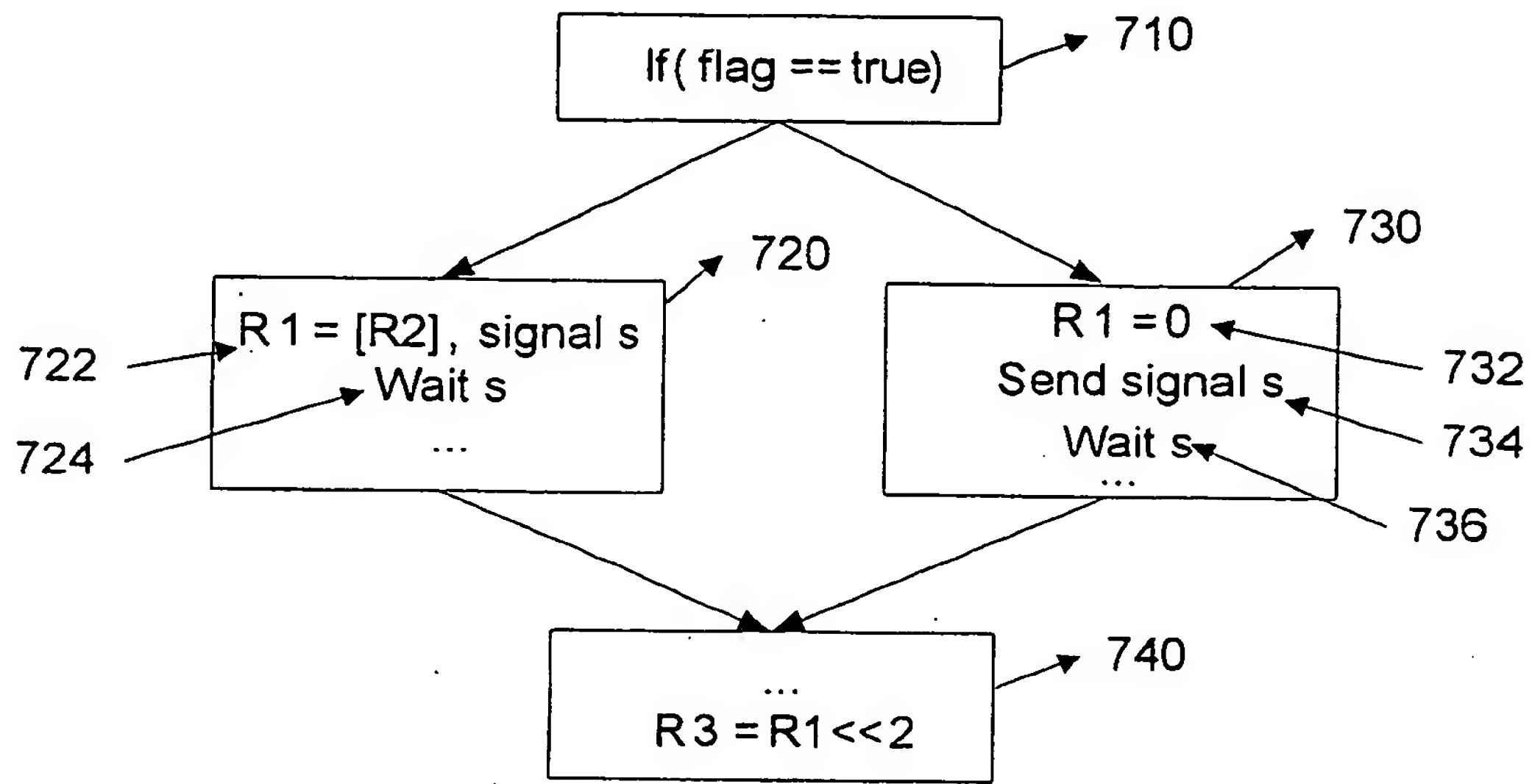


FIG. 7B

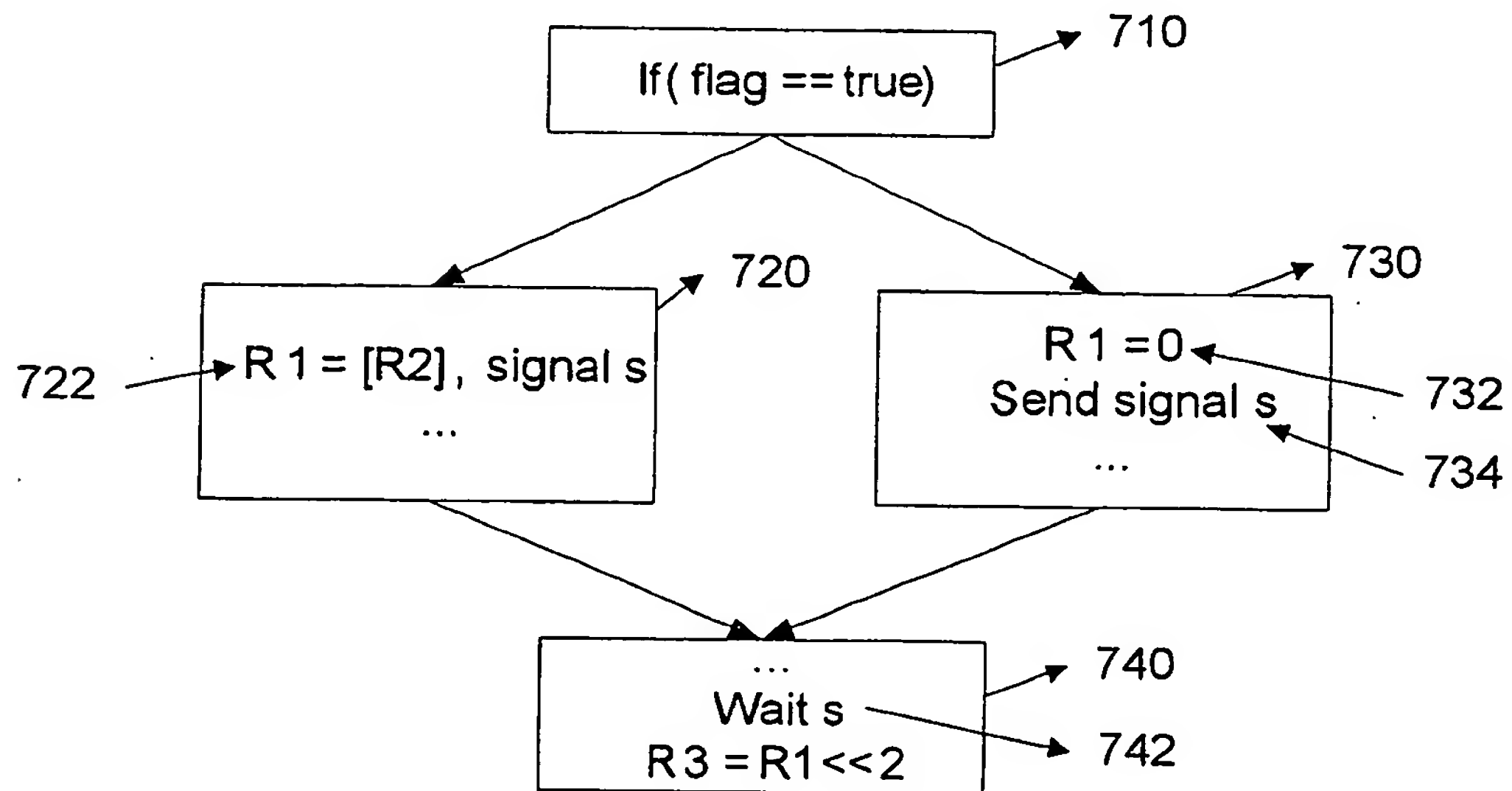


FIG. 7C

800

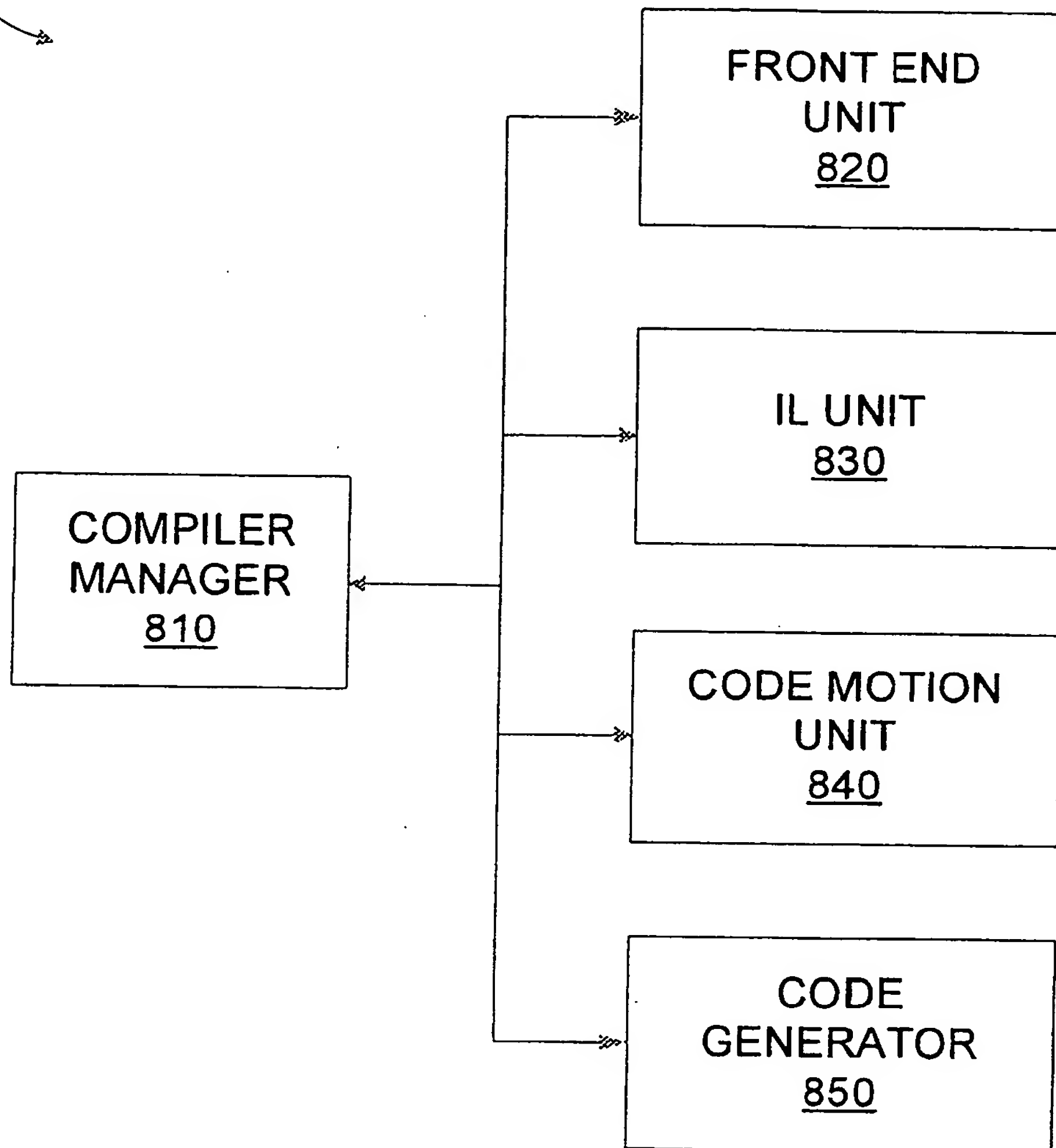


FIG. 8